

# **Time dependent partial differential equations**

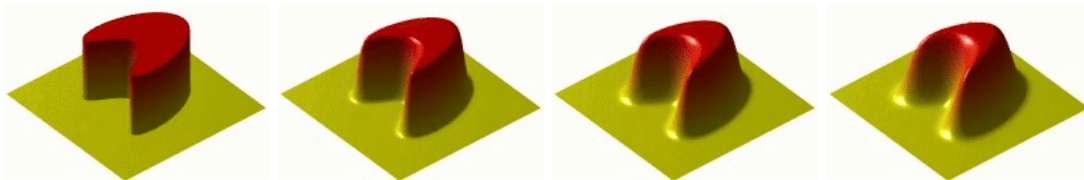
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# Agenda

1. The heat equation
  - Existence, uniqueness and regularity
2. The linear transport problem

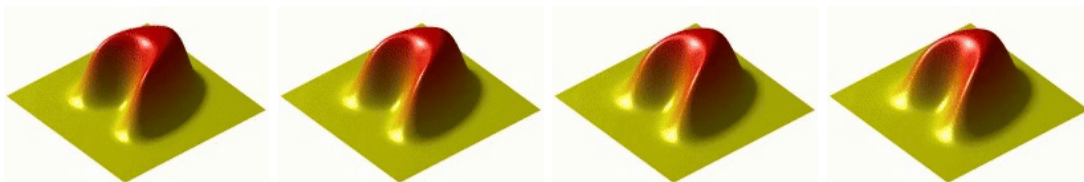


$$\partial_t u - \Delta u = f \text{ in } (0, T) \times \Omega$$

## Initial-Boundary Value Problem

$$u(x, t) = g(x, t) \quad x \in \partial\Omega$$

$$u(x, 0) = u_0(x) \quad x \in \Omega$$



## Type of equation

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- The heat equation can be considered as mixture of ODE and PDE
- This concept will also be important for the numerical approximation



## Variational formulation

Strong (classical) form

$$u \in C^1(I; C(\Omega)) \cap C(I; C^2(\Omega))$$

$$\partial_t u - \Delta u = f \text{ in } \Omega$$

**Lemma** Every strong solution is solution to the space-time variational formulation

$$u \in W = \{\phi \in L^2(I; H^1(\Omega)), \partial_t \phi \in L^2(I; L^2(\Omega)), \phi(0) = u_0\}$$

satisfying

$$I = ]0, T[ \quad H^{-1}(\Omega)$$

$$((\partial_t u, \phi)) + ((\nabla u, \nabla \phi)) = ((f, \phi)) \quad \forall \phi \in W,$$

where

$$((u, v)) = \int_0^T \int_{\Omega} u(x, t) v(x, t) \, dx \, dt.$$

*W is a  
Bochner-space*

Proof

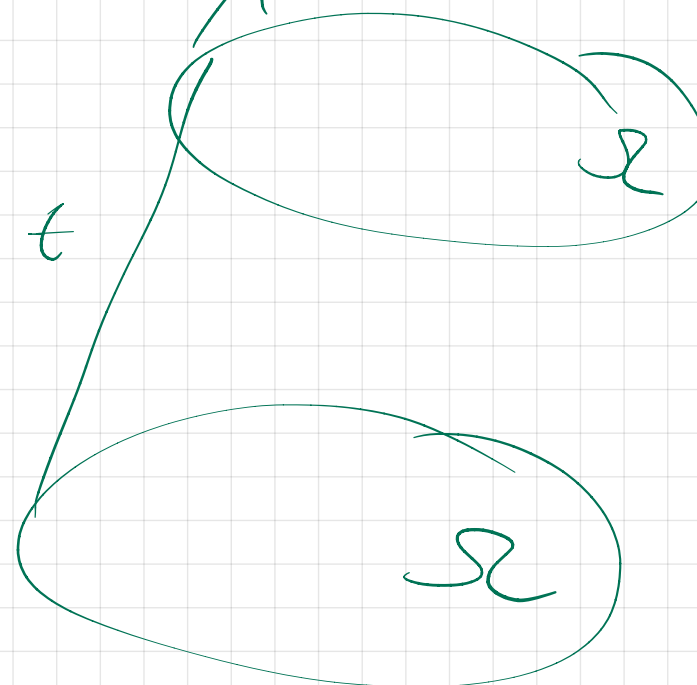
$$u_\epsilon - \Delta u = f$$

$$\text{for } \varphi \in V_0$$

$$\Leftrightarrow u_\epsilon \cdot \varphi - \Delta u \cdot \varphi = f \cdot \varphi \quad \int_0^T \int_\Omega \cdot$$

$$\varphi = 0 \text{ on } \partial\Omega$$

$$\Leftrightarrow \int_0^T \int_\Omega u_\epsilon(x,t) \cdot \varphi(x,t) - \Delta u(x,t) \varphi(x,t) dx dt = \int_0^T \int_\Omega f(x,t) \varphi(x,t) dx dt$$



$$\Leftrightarrow \int_0^T \int_\Omega u_\epsilon(x,t) \varphi(x,t) dx dt + \int_0^T \int_\Omega \underbrace{\nabla u(x,t) \cdot \nabla \varphi(x,t)}_{=0} dx dt = \int_0^T \int_\Omega f(x,t) \varphi(x,t) dx dt$$
$$= \int_0^T \int_{\partial\Omega} n \cdot \nabla u(x,t) \cdot \varphi(x,t) dx dt = \int_0^T \int_\Omega f(x,t) \varphi(x,t) dx dt$$

**Lemma** Let  $f \in L^2(I; L^2(\Omega))$ . For every variational solution  $u \in W$  to

$$((\partial_t u, \phi)) + ((\nabla u, \nabla \phi)) = ((f, \phi)) \quad \forall \phi \in W$$

it holds

$\forall T > 0$

$$\|u(T)\|^2 + \frac{1}{2} \int_0^T \|\nabla u(t)\|^2 dt \leq \|u(0)\|^2 + \frac{1}{2} \int_0^T \|f(t)\|^2 dt$$

Proof  $\varphi = u$

$$((\partial_t u, u)) + ((\nabla u, \nabla u)) = ((f, u))$$

$$(1) ((\nabla u, \nabla u)) = \int_0^T \int_{\Omega} \nabla u \cdot \nabla u \, dx \, dt = \int_0^T \|\nabla u(t)\|_{\Omega}^2 \, dt$$

$$(2) ((f, u)) = \int_0^T \int_{\Omega} f \cdot u \, dx \, dt = \int_0^T (f(t), u(t))_{\Omega} \, dt \leq \int_0^T \|f(t)\| \cdot \|u(t)\| \, dt$$

$$(f, u) \leq \int_0^T \|f(t)\| \cdot \|u(t)\| dt$$

Poincaré<sub>T</sub>

$$\leq \int_0^T \|f(t)\| \cdot c_p \|u(t)\| dt$$

Young  
 $\leq$

$$\frac{1}{2} c_p^2 \int_0^T \|f(t)\|^2 + \frac{1}{2} \int_0^T \|u(t)\|^2 dt$$

$$(3) (d_t u, u) = \int_0^T \int_{\Omega} (d_t u) \cdot u dx dt$$

$$= \frac{1}{2} \int_0^T \int_{\Omega} d_t (u^2) dx dt = \frac{1}{2} \int_0^T d_t \|u(t)\|_{\Omega}^2 dt$$

$$= \frac{1}{2} \|u(t)\|_{\Omega}^2 - \frac{1}{2} \|u(0)\|_{\Omega}^2$$

$$d_t(u \cdot u)$$

$$= d_t u \cdot u + u \cdot d_t u$$

$$= 2 \cdot d_t u \cdot u$$

$$\Rightarrow \frac{1}{2} \|u(T)\|^2 + \frac{1}{2} \int_0^T \|\nabla u(t)\|^2 dt \leq \frac{1}{2} \|u(0)\|^2 + \frac{c_p^2}{2} \int_0^T \|f(t)\|^2 dt$$

□

**Lemma** The variational solution  $u \in W$  is unique.

Proof Assume  $u_1, u_2 \in W$  are solutions

$$((d_t u_1, \varphi)) + ((\nabla u_1, \nabla \varphi)) = ((f, \varphi))$$

$$((d_t u_2, \varphi)) + ((\nabla u_2, \nabla \varphi)) = ((f, \varphi))$$

$$\Rightarrow ((d_t \underbrace{(u_1 - u_2)}_w, \varphi)) + ((\nabla (u_1 - u_2), \nabla \varphi)) = 0$$

$$\Rightarrow ((d_t w, \varphi)) + ((\nabla w, \nabla \varphi)) = 0$$

With stability - estimate

$$\Rightarrow \|\omega(t)\|^2 + \int_0^T \|\nabla \omega(t)\|^2 \leq \|\omega(0)\|^2$$

$$\omega(0) = u_1(0) - u_2(0) = 0$$

$$\Rightarrow \omega = 0$$

□

## Smoothing property

- The heat equation has the *smoothing property*: Even if the initial solution is rough, e.g. discontinuous, the solution is smooth for every  $t > 0$ .

Let  $\Omega$  be smooth.

**Lemma** Let  $u_0 \in L^2(\Omega)$  be the initial solution. For the homogenous problem

$$((\partial_t u, \phi)) + ((\nabla u, \nabla \phi)) = 0 \quad \forall \phi \in W,$$

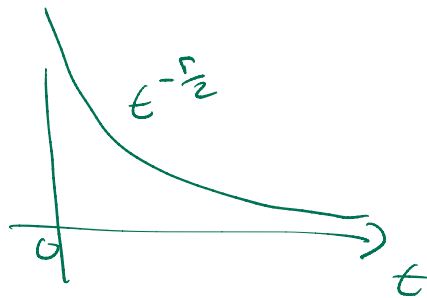
it holds for all  $r \in \mathbb{N}$

$$\|\nabla^r u(t)\| \leq c \cdot t^{-\frac{r}{2}} \cdot \|u_0\|_{L^2(\Omega)}$$

$t \rightarrow 0 \rightarrow \infty$

or: for  $t > 1$

$$\|\nabla^r u(t)\| \leq c \|u_0\|_{L^2(\Omega)}$$





Proof

(o) We know

$$\|u(T)\|^2 + \int_0^T \|\nabla u(t)\|^2 dt \leq \|u_0\|^2$$

$$\sigma = 0$$

$$\sigma = 1$$

Idea

$$\varphi = -\Delta u$$

$$-\Delta = \nabla \cdot \nabla = \operatorname{div} \nabla$$

$$((d_t u, -\Delta u)) + ((\nabla u, \nabla(-\Delta u))) = 0$$

$\Rightarrow$

$$((\nabla d_t u, \nabla u)) + \int_0^T \int_{\partial\Omega} d_t u \cdot (n \cdot \nabla u) ds dt$$

$$+ ((-\Delta u, -\Delta u)) - \int_0^T \int_{\partial\Omega} \nabla u \cdot (n \cdot \Delta u) dx dt$$

$$= 0$$

$\Rightarrow$

$$((d_t \nabla u, \nabla u)) + ((-\Delta u, -\Delta u)) = 0$$

$$\Leftrightarrow \int_0^T \frac{d}{dt} \|\nabla u(t)\|^2 dt + \int_0^T \|\Delta u(t)\|^2 dt = 0$$

$$\Leftrightarrow \frac{1}{2} \|\nabla u(T)\|^2 + \int_0^T \|\Delta u(t)\|^2 dt = \frac{1}{2} \|\nabla u_0\|^2$$

We showed: if  $u_0 \in H^1(\Omega)$  then

$u(t) \in H^1(\Omega)$  and  $u \in L^2(I; H^2(\Omega))$

But: We want to show  $u(t) \in H^1(\Omega)$  for  $u_0 \in L^2(\Omega) \forall$

Proof with "smoothing". Trick: add Factor "z"

$$\varphi = -t \cdot \Delta u$$

$$((d_t u, -t \Delta u)) + ((\nabla u, \nabla (-t \Delta u)) = 0$$

(=)

$$\int_0^T t \|\Delta u(t)\|^2 dt$$

$$((d_t \nabla u, t \nabla u)) + ((-\Delta u, -t \Delta u)) = 0$$

on the side

$$d_t (t \|\nabla u\|^2)$$

$$= d_t \|\nabla u\|^2 \cdot t + \|\nabla u\|^2$$

$$= 2 \left( \nabla d_t u, t \cdot \nabla u \right) + \|\nabla u\|^2$$

$$((d_t \nabla u, t \nabla u)) = \frac{1}{2} \int_0^T d_t (t \|\nabla u\|^2) dt - \frac{1}{2} \int_0^T \|\nabla u(t)\|^2 dt$$

$$= \frac{1}{2} T \|\nabla u(T)\|^2 - 0 - \frac{1}{2} \int_0^T \|\nabla u(t)\|^2 dt$$

$$\frac{T}{2} \|\nabla u(T)\|^2 + \int_0^T t \cdot \|\Delta u(t)\|^2 dt = 0 + \frac{1}{2} \int_0^T \|\nabla u(t)\|^2 dt$$

$$\Rightarrow c_s \|u\|_{H^2}^2$$

$$\leq \frac{1}{2} \|u_0\|^2$$

$$\tau=1 \quad \|\nabla u(t)\|^2 + \frac{2}{T} \int_0^T t \|\Delta u(t)\|^2 dt \leq \frac{1}{T} \|u_0\|^2$$

General

$$\varphi = (-\Delta u)^\tau \cdot t^\tau$$

$$\tau = 0, 1, 2, \dots$$

# General Proof

$$((d_t u, \varphi)) + ((\nabla u, \nabla \varphi)) = 0$$

$$\varphi = \varepsilon^\Gamma (-\Delta^\Gamma u)$$

$$((d_t u, \varepsilon^\Gamma (-\Delta^\Gamma u))) + ((\nabla u, \varepsilon^\Gamma (-\Delta^\Gamma u))) = 0$$

$\swarrow$   $\nwarrow$   
 $\Gamma$ -times partial integration

$$(-\Delta)^\Gamma = (-\operatorname{div} \nabla)^\Gamma$$

$\Leftrightarrow$

$$\underbrace{((d_t \nabla^\Gamma u, \varepsilon^\Gamma \nabla^\Gamma u))} + \underbrace{((\nabla^{\Gamma+1} u, \varepsilon^\Gamma \nabla^{\Gamma+1} u))} = 0$$

$$= \frac{1}{2} \int_0^T d_t (\varepsilon^\Gamma \|\nabla^\Gamma u\|^2) dt$$

$$- \frac{1}{2} \int_0^T \Gamma \cdot \varepsilon^{\Gamma-1} \|\nabla^\Gamma u\|^2 dt$$

$$= \int_0^T \varepsilon^\Gamma \|\nabla^{\Gamma+1} u\|^2 dt$$

$$\Leftrightarrow \underbrace{\frac{1}{2} \int_0^T d_t (t^\Gamma \|\nabla^\Gamma u\|^2) dt + \int_0^T t^\Gamma \|\nabla^{\Gamma+1} u\|^2 dt}_{\leq \frac{\Gamma}{2} \int_0^T t^{\Gamma-1} \|\nabla^\Gamma u(t)\|^2 dt}$$

$$= \frac{1}{2} T^\Gamma \|\nabla^\Gamma u(T)\|^2 = 0$$

$$\Leftrightarrow \textcircled{*} \quad T^\Gamma \|\nabla^\Gamma u(T)\|^2 + 2 \int_0^T t^\Gamma \|\nabla^{\Gamma+1} u\|^2 dt \leq \Gamma \cdot \int_0^T t^{\Gamma-1} \|\nabla^\Gamma u(t)\|^2 dt$$

$\int_0^T t^{\Gamma-1} \|\nabla^\Gamma u(t)\|^2 dt$  is estimated using  $\textcircled{*}$  for  $\Gamma=1$

$$\Rightarrow \int_0^T t^{\Gamma-1} \|\nabla^\Gamma u(t)\|^2 dt \leq C \cdot \int_0^T t^{\Gamma-2} \|\nabla^{\Gamma-1} u\|^2 dt \leq \dots \leq C \cdot \int_0^T \|u\|^2 dt \leq C \|u\|^2$$